

# Deep Multigrid: learning restriction and prolongation matrices<sup>1</sup>

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<sup>1</sup><https://arxiv.org/abs/1711.03825>

# General idea

## Problem parametrization

- Parametrization fixes parameters set
- Parametrization controls the quality
- Parametrization gives differentiable steps

## Loss function or its upper bound

- Computable in reasonable time
- Differentiable
- Stochastic gradient

## Example: geometric multigrid method

- Parameters: restriction and prolongation operators
- Differentiable steps
- Loss function — ?

# Problem statement

- Partial differential equation  
Domain is the segment  $[0, 1]$  and boundary conditions are  $u(0) = 0, u(1) = 0$ .
- Discretization: introducing  $n$  points mesh and finite differences approximation

- Linear system:

$$Au = f$$

- Grid step:  $h = \frac{1}{n+1}$

# Two-grid idea

1. Perform  $s_1$  steps of iterative process for  $u^{(k)}$
2. Compute residual  $r^{(k)} = Au^{(k)} - f$
3. Restrict  $r^{(k)}$  on coarse grid:  $r_c^{(k)} = Rr^{(k)}$
4. Project  $A$  on coarse grid:  $A_c = RAP$
5. **Solve system**  $A_c u_c^{(k)} = r_c^{(k)}$
6. Update  $u^{(k)}$ :  $\hat{u}^{(k)} = u^{(k)} + Pu_c^{(k)}$
7. Perform  $s_2$  steps of iterative process for  $\hat{u}^{(k)}$ , get  $u^{(k+1)}$

## Multigrid

Projection onto coarse grid can perform recursively in **step 5**

# Two-grid as iterative process

Two-grid method is an iterative process

$$u^{(k+1)} = Cu^{(k)} + b$$

with the following iteration matrix

and 
$$C = (M_2^{-1}K_2)^{s_2}(I + P(RAP)^{-1}RA)(M_1^{-1}K_1)^{s_1}$$

$$b = ((M_2^{-1}K_2)^{s_2}P(RAP)^{-1}R(s_1AM_1^{-1} - I) + s_2M_2^{-1})f.$$

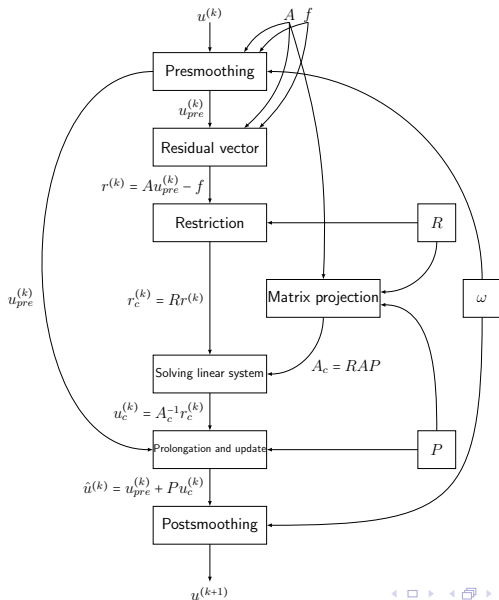
Pre- and postsmoothing — **damped** Jacobi method

- $M_1 = M_2 = \omega^{-1}D$
- $K_1 = K_2 = \omega^{-1}D - A$

Iterative process analysis

- The matrix  $C$  depends on  $R, P$  and  $\omega$
- Matrix-by-vector product  $Cx$  is one iteration of the two-grid method with  $u^{(k)} \equiv x$

# Neural Network reformulation



# Parametrization

## Matrices

- Restriction matrix  $R \in \mathbb{R}^{m \times n}$ ,  $m = \frac{n-1}{2}$
- Prolongation matrix  $P \in \mathbb{R}^{n \times m}$ ,  $m = \frac{n-1}{2}$

## Constraints on matrices

- **Non-symmetric, non-homogeneous** —  $3m$  numbers
- Symmetric, non-homogeneous —  $2m$  numbers
- Non-symmetric, homogeneous — 3 numbers
- Symmetric, homogeneous — 2 numbers

## Scalar

Damp factor  $\omega \in \mathbb{R}_{++}$

# Optimization problem

## Loss function — spectral radius

$$\rho(C) = \max_{i=1,\dots,n} |\lambda_i(C)| \rightarrow \min_{R,P,\omega}$$

Hard to optimize! ☹️

## Gelfand formula

$$\rho(A) = \lim_{k \rightarrow \infty} \sqrt[k]{\|A^k\|}$$

Use approximation! 😊

## Bounds

For any positive integer  $K$ :

$$\gamma^{(1+\ln K)/K} \|A^K\|_F^{1/K} \leq \rho(A) \leq \|A^K\|_F^{1/K}, \quad \gamma \in (0, 1)$$



# Upper bound minimization

- Stochastic approximation from Hutchinson's estimator:

$$\|A^K\|_F^2 = \mathbb{E}_z \|A^K z\|_2^2,$$

where  $z = [z_i]$ , such that

- $z_i \in \mathcal{N}(0, I)$
- $z_i \in \mathcal{R}$  ( $\mathbb{P}(z_i = \pm 1) = \frac{1}{2}$ ) — less variance

## Optimization problem

$$F_K = \mathbb{E}_z \|C^K z\|_2^2 \rightarrow \min_{R, P, \omega}$$

## Unbiased estimation

$$\hat{F}_K = \frac{1}{N} \sum_{i=1}^N \|C^K z^i\|_2^2$$

# How to minimize?

- Stochastic gradient based method (SGD, AdaDelta, **Adam**, ...)
- Autodiff tool: **Autograd**, PyTorch, Theano, etc...
- Custom gradient implementations for some layers
- Baur-Strassen's theorem
- Initialization is crucial!

# Initialization

- The problem is strongly non-convex
- Linear interpolation is good for Poisson equation

$$R_{\text{lin}} = \frac{1}{4} \begin{bmatrix} 1 & 2 & 1 & & & & \\ & & 1 & 2 & 1 & & \\ & & & & 1 & 2 & 1 \\ & & & & & 1 & 2 & 1 \end{bmatrix} \quad P_{\text{lin}} = \frac{1}{2} \begin{bmatrix} 1 & & & & & & \\ 2 & & & & & & \\ 1 & 1 & & & & & \\ & 2 & & & & & \\ & 1 & 1 & & & & \\ & & 2 & & & & \\ & & 1 & & & & \\ & & & 1 & & & \end{bmatrix}$$

- But stuck in poor local minima in more complex cases
- How to deal with this issue?

- Homotopy with start matrix  $A_0$  and target matrix  $A_1$ 
  - Consider sequence of matrix

$$M_i = \alpha_i A_1 + (1 - \alpha_i) A_0,$$

$$\alpha_0 = 0, 0 < \alpha_1 < \alpha_2 < \dots < \alpha_{k-1} < 1, \alpha_k = 1$$

- Solution of the  $i$ -th problem is initialization for the  $(i + 1)$ -th problem
- Grid of  $\alpha_i$  is adaptive with acceptance rate  $\tau$

# Model 1D problems

- Poisson equation:  $-\Delta u = f$

$$A = -\frac{1}{h^2} \begin{bmatrix} -2 & 1 & & & & \\ 1 & -2 & 1 & & & \\ & \ddots & \ddots & \ddots & & \\ & & 1 & -2 & 1 & \\ & & & 1 & -2 & \\ & & & & & -2 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

- Helmholtz equation:  $-\Delta u - k^2 u = f$ 
  - low frequency:  $k \approx 10$
  - high frequency:  $k \gtrsim 100$
  - piece-wise constant  $k(x)$ :

$$k(x) = \begin{cases} 1, & 0 \leq x < 0.5 \\ k_{\max}, & 0.5 \leq x \leq 1. \end{cases}$$

- Stationary singularly-perturbed diffusion-convection equation

# Poisson equation

Spectral radii  $\rho$  for the compared methods

| Grid size | Linear   | AMG      | DMG      |
|-----------|----------|----------|----------|
| 7         | 0.061728 | 0.182358 | 0.015088 |
| 15        | 0.061728 | 0.193726 | 0.018481 |
| 31        | 0.061728 | 0.196578 | 0.027819 |
| 63        | 0.061728 | 0.197207 | 0.045068 |
| 127       | 0.061728 | 0.195878 | 0.045400 |

# Helmholtz equation: low frequency

Spectral radii  $\rho$  for the compared methods

| Grid size | $k$ | Linear   | AMG      | DMG      |
|-----------|-----|----------|----------|----------|
| 7         | 5   | 0.226356 | 0.226214 | 0.012505 |
| 13        | 10  | 1.808608 | 0.255912 | 0.044337 |
| 17        | 15  | 0.826753 | 0.406821 | 0.062037 |
| 23        | 20  | 3.388036 | 0.418464 | 0.067183 |

# Helmholtz equation: high frequency

Spectral radii  $\rho$  for the compared methods, grid size  $n = 1115$

| $k$  | Linear      | AMG      | DMG      |
|------|-------------|----------|----------|
| 100  | 0.180680    | 0.198093 | 0.061088 |
| 300  | 13.389492   | 0.203956 | 0.053827 |
| 500  | 14.608550   | 0.218872 | 0.066820 |
| 700  | 99.555631   | 0.243871 | 0.060205 |
| 900  | 62.940589   | 0.377024 | 0.091268 |
| 1000 | 4789.842424 | 0.607620 | 0.116077 |

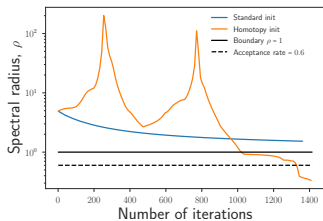


# Helmholtz equation: non-constant $k(x)$

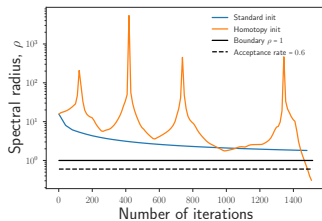
Spectral radii  $\rho$  for the compared methods

| Grid size | $k_{\max}$ | Linear   | AMG      | DMG      |
|-----------|------------|----------|----------|----------|
| 127       | 100        | 3.147622 | 0.330212 | 0.078162 |
| 255       | 100        | 1.642432 | 0.212405 | 0.047063 |
| 511       | 100        | 0.194238 | 0.200955 | 0.055769 |

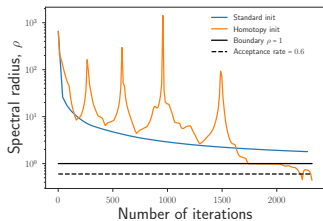
# Homotopy performance — $3m$ numbers



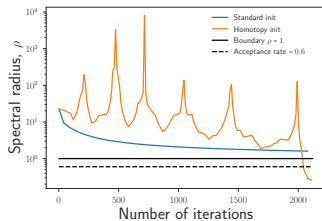
$$k = 100, n = 113$$



$$k = 150, n = 169$$

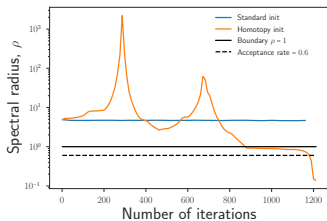


$$k = 200, n = 223$$

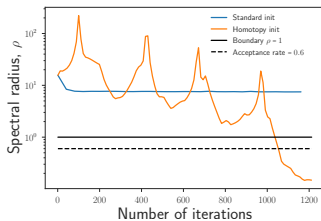


$$k = 250, n = 279$$

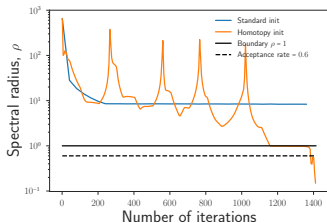
# Homotopy performance — 2 numbers



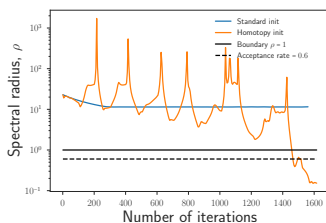
$$k = 100, n = 113$$



$$k = 150, n = 169$$

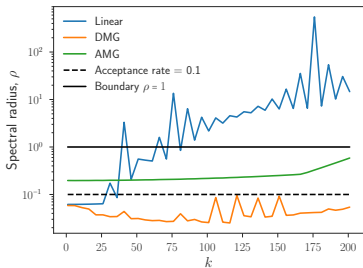


$$k = 200, n = 223$$

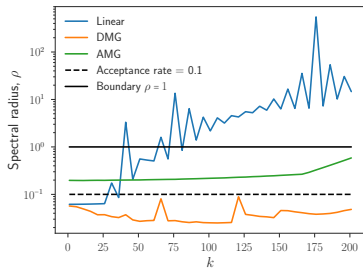


$$k = 250, n = 279$$

# Moving frequency from low to high



$3m$  numbers



2 numbers

# Stationary diffusion-convection equation

$$-\varepsilon \frac{d^2 u(x)}{dx^2} + \frac{du(x)}{dx} = f(x), \quad u(0) = 0, \quad u(1) = 0$$

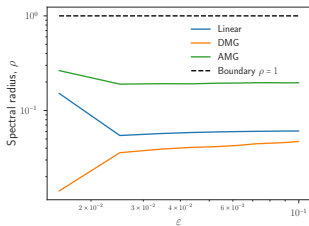
Non-symmetric matrix  $A$ :

$$A = -\frac{\varepsilon}{h^2} \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & -2 & 1 \\ & & & 1 & -2 \end{bmatrix} + \frac{1}{h} \begin{bmatrix} -1 & 1 & & & \\ 0 & -1 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & -1 & 1 \\ & & & 0 & -1 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

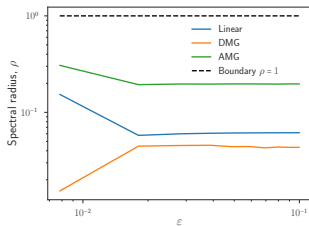
Boundary layer

Grid has to cover boundary layer  $\rightarrow h < \varepsilon$ .

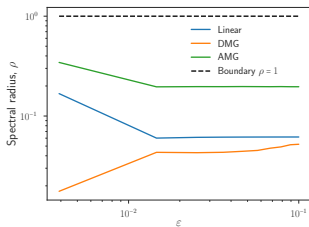
# Methods comparison



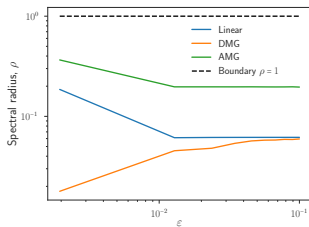
$n = 63$



$n = 127$



$n = 255$



$n = 511$

# Summary

- General approach to find locally optimal parameters through NN reformulation
- Unbiased estimation of the loss function for iterative process
- Method to find locally optimal parameters for the two-grid method
- Homotopy initialization
- Robustness under different constraints on the operators

# Future work

- Extend to 2D case — almost done
- Optimize sparse preconditioners
- Use GPU-based framework
- Extend approach to other problems